

1) The matrix  $A$  is row equivalent to  $U$  (see below). Find a basis for  $N(A)$ , and explain briefly how you know it is a basis.

$$A = \begin{pmatrix} 1 & 3 & 0 & 9 & 4 \\ 1 & 1 & 4 & 19 & 2 \\ 1 & 1 & 2 & 11 & 2 \end{pmatrix} \quad U = \begin{pmatrix} 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 3 & 1 \\ 0 & 0 & 1 & 4 & 0 \end{pmatrix}$$

2) Which of the following sets  $S$  are subspaces of  $R^2$ ? Explain each answer briefly.

a)  $S = \{(x_1, x_2)^T \mid 3x_1 + 4x_2 = 7\}$

b)  $S = \{(x_1, x_2)^T \mid x_1 = x_2\}$

c)  $S = \{(x_1, x_2)^T \mid x_1 = x_1\}$

d)  $S = \{(x_1, x_2)^T \mid x_1^2 + x_2^2 = 0\}$

3) Choose ONE of these to prove. You can answer on the back.

a) If  $\dim(V) = n > 0$  and  $B = \{v_1, v_2, \dots, v_n\}$  spans  $V$  then  $B$  is a basis of  $V$ .

b) Show that a nonempty subset of a linearly independent set of vectors  $\{v_1, v_2, \dots, v_n\}$  is also linearly independent.

c) Let  $L = \{v_1, v_2, \dots, v_n\}$  be a spanning set of  $V$  and let  $v \in V$  be any other vector. Show that  $\{v_1, v_2, \dots, v_n, v\}$  is linearly dependent.

Extra Credit (about 3-5 points): Should a Linear Algebra course include MATLAB in the lectures and homework? Why, or why not?

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Answers: The average grade was about 35/60.

1) Find the solution set to  $Ax = 0$  from  $U$ . After factoring out the  $\alpha$  and  $\beta$ , you should get  $N(A) = \text{span} \{[0 \ -3 \ -4 \ 1 \ 0]^T, [-1 \ -1 \ 0 \ 0 \ 1]^T\}$ . Since these two are not scalar multiples of each other they are LI and are a basis.

2) I accepted various explanations. For example, it is OK to check the closure properties. But here are the simplest answers:

2a) No.  $S$  does not contain the zero vector.

2b) Yes.  $S = \text{span} \{[1 \ 1]^T\}$ .

2c) Yes.  $S = R^2$ .

2d) Yes.  $S = \{\mathbf{0}\}$ .

3) a) is part of the "2/3 theorem" and is in the book. The other two were HW:

3b) We can assume the subset is the shortened list,  $\{v_1, v_2, \dots, v_j\}$  where  $1 \leq j \leq n$ . We can assume that  $c_1v_1 + \dots + c_jv_j = 0$  and must prove the  $c$ 's are all zero. But by adding

in zeroes, we can change this equation to  $c_1v_1 + \dots c_jv_j + 0v_{j+1} + \dots 0v_n = 0$ . Since the original list is LI, all the  $c$ 's have to be zero. Done.

3c) Since  $v \in \text{span}(L)$ , we get  $c_1v_1 + \dots c_nv_n = v$ . And by subtracting,  $c_1v_1 + \dots c_nv_n - v = 0$ . The coefficient of  $v$  is not zero, so this shows LD.

The answers to the bonus question were mostly positive, especially about including MATLAB in the lectures (about 7-1). Most people also think it should be part of the HW (about 5-3) but several people consider it too time-consuming. Compared to other semesters, there were almost no complaints about not understanding the exercises or the MATLAB commands.